

ON THE PROBLEM OF THE TWO-BODIES OF VARIABLE MASS

SIMION BOGÎLDEA

High School “Regele Ferdinand”, Sighetu Marmatiei, Romania
E-mail address: sbogildea@yahoo.com

Received October 15, 2011

Abstract. In this paper we intend to present an analytical solution of the problem which refers to the increase of the major semi-axis of the planetary orbits in the case of the two-bodies in the second-order of approximation. The obtained results are compared with those reported by Vescan [9] for the first-order approximation and with those obtained numerically from the established basic equations.

Key words: gravitation-stars: variable mass-mass loss-celestial mechanics-two body problem; methods: analytical and numerical results.

1. INTRODUCTION

Many studies were done in the 20th century on celestial mechanics which lead to systems of differential equations that model the two-body problem in the case of variable mass. An example is the problem studied by the Romanian physicist Vescan [9] who studied in his PhD thesis the influence of variation of solar mass (as a result of solar radiation) about the major semi-axis of the planetary orbits. This interesting problem is an astronomical application of the two-body problem in the case of variable mass, a problem which was studied for the first time by the Swedish astronomer Gylden [1].

Problems connected by the motion of celestial bodies with variable mass, which refer to the decrease of the mass as a result of corpuscular star radiation have had a great importance in the last several decades. In these studies it is usually considered that the law of mass variation of a star (particularly of the Sun) is of the following form

$$\frac{dM}{dt} = -\alpha M^n, \quad (1)$$

where α is a constant and n is a positive real number. We notice that the case $n=1$ corresponds to the law of mass variation used by Vescan [9] and the case $n=2$ was studied by Meshcherskii [5]. Many papers which have studied the laws

of mass variation of the central body and the problem of the two-bodies with decreasing mass can be found in the literature, such as, for example, by Jeans [4], Hadjidemetriou [2, 3], Schröder and Smith [8]. Some refined analytical solutions are given in the paper Pal *et al.* [7].

In this article we will use the linear expression of the mass variation to establish the differential equation of the trajectory, the form of planetary orbits and the increase of the major semi-axis in the approximation of the second-order. The obtained analytical solution is compared with the results reported by Vescan [9] and with those resulted from the integration of equations using numerical methods. The obtained results show a very good agreement between them.

2. THE BASIC EQUATIONS

By analogy with the radioactivity, Vescan [9] has considered the law of variation of mass solar of the form

$$\mu = \mu_0 e^{-qt}, \quad (2)$$

where q is a very small constant, t is the time and μ_0 is the mass of the Sun at the initial time (initial moment) t_0 . By development in series and limiting to the first two terms, it results in the following linear expression

$$e^{-qt} = 1 - qt. \quad (3)$$

Then, the Newton's law of attraction between the Sun and the planet of mass m can be written as

$$F = -k \frac{m\mu_0}{r^2} (1 - qt). \quad (4)$$

In order to obtain the equation of the planetary orbit, Vescan [9] has used Picard's successive approximation method and obtained the following equation of the trajectory

$$r(\theta) = \frac{a(1-e^2)}{1+e \cos\theta} \left(1 + \frac{qa^2\theta}{\sqrt{ka\mu_0}} \right). \quad (5)$$

This equation shows that the trajectory of one planet has the form of an elliptical spiral or an increasing rosette. The increase of the major semi-axis during the revolution Δa_v obtained by Vescan [9] is

$$\Delta a_v = \frac{2\pi qa^3}{\sqrt{ka\mu_0}}. \quad (6)$$

3. DIFFERENTIAL EQUATION OF THE TRAJECTORY

Because the attraction force is a central one, we have

$$r^2 \dot{\theta} = C, \quad (7)$$

where C is the constant area which has the expression

$$C = \sqrt{k a \mu_0 (1 - e^2)}, \quad (8)$$

Then, the Newton's law (4) becomes

$$F = -\frac{k m \mu_0}{r^2} \left[1 - \frac{a}{c} \int_0^\theta r^2(x) dx \right], \quad (9)$$

where

$$r(\theta) = \frac{b^2}{a(1 + e \cos \theta)} \quad (10)$$

is an even function. The expression of $r^2(\theta)$ developed in a Fourier trigonometrically series is given by

$$r^2 = \frac{b^4}{a^2} (1 + e \cos \theta)^{-2} = \frac{b^4}{a^2} \left[\frac{1}{2\pi} \int_{-\pi}^{\pi} (1 + e \cos x)^{-2} dx + \sum_{n=1}^{\infty} \frac{\cos n\theta}{\pi} \int_{-\pi}^{\pi} (1 + e \cos x)^{-2} \cos nx dx \right]. \quad (11)$$

For the approximation of the second order ($n = 2$), we have

$$\begin{aligned} \int_{-\pi}^{\pi} (1 + e \cos x)^{-2} dx &= \frac{2\pi}{(1 - e^2)^{\frac{3}{2}}}, \\ \int_{-\pi}^{\pi} \frac{\cos x}{(1 + e \cos x)^2} dx &= -\frac{2e\pi}{(1 - e^2)^{\frac{3}{2}}}, \\ \int_{-\pi}^{\pi} \frac{\cos 2x}{(1 + e \cos x)^2} dx &= \frac{2\pi[2(1 - e^2)^{\frac{3}{2}} + 3e^2 - 2]}{(1 - e^2)^{\frac{5}{2}} e^2}. \end{aligned} \quad (12)$$

On the other hand, from (9) we get

$$\int_0^\theta r^2 d\theta = \frac{b^4}{a^2(1 - e^2)^{\frac{3}{2}}} \left[\theta - 2e \sin \theta + \frac{2(1 - e^2)^{\frac{3}{2}} + 3e^2 - 2}{e^2} \sin 2\theta \right]. \quad (13)$$

Using Binet's formula

$$\frac{d^2}{d\theta^2} \left(\frac{1}{r} \right) + \frac{1}{r} = -\frac{F r^2}{m C^2} \quad (14)$$

together with the equations (9) and (13) it obtains

$$\frac{\alpha^2}{d\theta^2} \left(\frac{1}{r} \right) + \frac{1}{r} = \frac{k\mu_0}{c^2} \left[1 - \frac{qb^4}{c \alpha^2 (1-e^2)^{\frac{3}{2}}} (\theta - 2e \sin \theta + \frac{2(1-e^2)^{\frac{3}{2}} + 3e^2 - 2}{e^2} \sin 2\theta) \right], \quad (15)$$

and it represents the differential equation of trajectory.

4. THE FORM OF THE PLANETARY ORBITS AND THE EXTENSION OF THE MAJOR SEMI-AXIS

In order to solve equation (15) we look for a solution of the form

$$\frac{1}{r} = \frac{k\mu_0}{c^2} (1 + e \cos \theta) \psi(\theta) \quad (16)$$

where $\psi(\theta)$ is a correction factor. Using (15) and (16) it is found that the function $\psi(\theta)$ must satisfy the ordinary differential equation

$$(1 + e \cos \theta) \psi'' - 2e \sin \theta \psi' + \psi = 1 - \frac{qb^4}{c \alpha^2 (1-e^2)^{\frac{3}{2}}} (\theta - 2e \sin \theta + \frac{2(1-e^2)^{\frac{3}{2}} + 3e^2 - 2}{e^2} \sin 2\theta), \quad (17)$$

where the prime denotes differentiation with respect to θ . Further, using the form of equation (17), we assume that its solution is given by

$$\psi = M + \alpha \theta + \frac{\beta}{2} \theta^2 + \frac{\gamma}{3} \theta^3, \quad (18)$$

where M , α , β and γ are unknown functions of θ having very small numerical values for $\theta \in (0, 2\pi)$. Substituting (18) into (17), we get, by the identification of θ^3 , θ , $\sin \theta$ and $\cos \theta$ the following algebraic system

$$M + \beta = 1,$$

$$\alpha + 2\gamma = -\frac{qb^4}{c \alpha^2 (1-e^2)^{\frac{3}{2}}} = -\frac{q\alpha^2}{\sqrt{k\alpha\mu_0}}, \quad \beta + 2\gamma\theta = 0,$$

$$\alpha + \beta\theta = -\frac{q\alpha^2}{\sqrt{k\alpha\mu_0}} \left(1 - \frac{2(1-e^2)^{\frac{3}{2}} + 3e^2 - 2}{e^2} \cos \theta \right). \quad (19)$$

The solution of this system is

$$M = 1 - \beta.$$

$$\begin{aligned}\alpha &= -\frac{qb^4}{C\alpha^2(1-e^2)^{\frac{3}{2}}}\left[1 - \frac{2(1-e^2)^{\frac{3}{2}} + 3e^2 - 2}{e^3} \cdot \frac{\cos\theta}{1+\theta^2}\right]; \\ \beta &= \frac{qb^4[2(1-e^2)^{\frac{3}{2}} + 3e^2 - 2]}{C\alpha^2(1-e^2)^{\frac{3}{2}}e^3} \cdot \frac{\theta\cos\theta}{1+\theta^2}; \\ \gamma &= -\frac{qb^4[2(1-e^2)^{\frac{3}{2}} + 3e^2 - 2]}{C\alpha^2(1-e^2)^{\frac{3}{2}}e^3} \cdot \frac{\cos\theta}{2(1+\theta^2)}.\end{aligned}\quad (20)$$

Thus (18) becomes

$$\Psi = 1 - \frac{qa^2}{\sqrt{k\alpha\mu_0}}\theta + \frac{qa^2}{\sqrt{k\alpha\mu_0}} \cdot \frac{2(1-e^2)^{\frac{3}{2}} + 3e^2 - 2}{e^3} \cdot \frac{\theta^3\cos\theta}{3(1+\theta^2)}.\quad (21)$$

From (16) and (21) we get the form of the planetary orbits:

$$r(\theta) \approx \frac{a(1-e^2)}{1+e\cos\theta} \left[1 + \frac{qa^2\theta}{\sqrt{k\alpha\mu_0}} - \frac{qa^2}{\sqrt{k\alpha\mu_0}} \cdot \frac{2(1-e^2)^{\frac{3}{2}} + 3e^2 - 2}{e^3} \cdot \frac{\theta^3\cos\theta}{3(1+\theta^2)}\right].\quad (22)$$

From the expression (22) it can be seen that one more term appears besides the result obtained by Vescan [9] in his equation (5). Thus, the extension of the major semi-axis during a revolution is given by

$$\Delta a_1 = \Delta a_v \left[1 + \frac{2(1-e^2)^{\frac{3}{2}} + 3e^2 - 2}{e^3} \cdot \frac{\pi^2(13+9\pi^2)}{3(1+\pi^2)(1+9\pi^2)}\right].\quad (23)$$

5. NUMERICAL RESULTS

On the other side, we determine numerically the quantity

$$\Delta a = a(2\pi) - a(0),\quad (24)$$

using the following system (see Muchametkalieva and Omarov [6]; Hadjidemetriou, J. [2, 3])

$$\begin{aligned}\frac{da}{dt} &= -\frac{a(1+2e\cos\theta+e^2)}{1-e^2} \cdot \frac{1}{\mu} \cdot \frac{d\mu}{dt}, \\ \frac{de}{dt} &= -(e + \cos\theta) \cdot \frac{1}{\mu} \cdot \frac{d\mu}{dt}, \\ \frac{d\omega}{dt} &= -\frac{\sin\theta}{e} \cdot \frac{1}{\mu} \cdot \frac{d\mu}{dt},\end{aligned}$$

$$\frac{d\theta}{dt} = \frac{C(1 + e \cos \theta)^2}{a^2(1 - e^2)^2} + \frac{\sin \theta}{e} \cdot \frac{1}{\mu} \cdot \frac{d\mu}{dt};$$

$$\frac{d\mu}{dt} = -q\mu, \quad (25)$$

where a , e , ω , θ and μ represent the major semi-axis, the eccentricity, the argument of the perihelion, the true anomaly and the mass of the Sun.

The system (25) was integrated numerically for a revolution using a Fehlberg fourth-fifth order Runge-Kutta method (MAPLE, rkf45) for the values of the quantities q , K and μ_0 considered by Vescan [9]

$$q = 5 \cdot 10^{-21} s^{-1}, k = 6,65 \cdot 10^{-8} \frac{cm^3}{g \cdot s^2}, \mu_0 = 2 \cdot 10^{33} g. \quad (26)$$

The initial values (at the time $t = 0$) of the parameters a , e , ω and θ are given in Table 1.

6. CONCLUSIONS

The aim of this paper is to determine analytically the expressions of Δa_1 given by (23) and numerically the expression of Δa . The results are presented in Table 2 where there are included also the analytical results obtained by Vescan [9] given by Eqs. (6). Comparing the results given in this table, obtained using the analytical and numerical solutions it can be concluded that there is a good agreement between them. Therefore, we are confident that the system (25) can be used also for the present problem. On the other hand, from the numerical integration of the system (25) it has been found that the variation of the eccentricity is oscillating on time. But, the amplitude of the oscillation is very small (taking as an example the Earth the difference between the maximum and minimum for ten years is of order 10^{-14} and for one thousand years it is 10^{-11}), that means that the variation of the eccentricity is very small. It means that the eccentricity is constant. This results is in very good agreement with the that obtained by Jeans [4].

Table 1

Values of a_0 , e_0 , ω_0 and θ_0 at the initial time, $t = 0$

Planet	$a_0 = a(0)$ (cm)	$e_0 = e(0)$	$\omega_0 = \omega(0)$ (rad/s)	$\theta_0 = \theta(0)$ (rad)
Mercury	$5.8 \cdot 10^{12}$	0.205631752	$\frac{2\pi}{365.25 \cdot 24 \cdot 3600 \cdot 0.241}$	0
Venus	$1.08 \cdot 10^{13}$	0.006771882	$\frac{2\pi}{365.25 \cdot 24 \cdot 3600 \cdot 0.615}$	0

Table 1 (continued)

Earth	$1.5 \cdot 10^{13}$	0.016708617	$\frac{2\pi}{365.25 \cdot 24 \cdot 3600}$	0
Mars	$2.3 \cdot 10^{13}$	0.09340062	$\frac{2\pi}{365.25 \cdot 24 \cdot 3600 \cdot 1.881}$	0
Jupiter	$7.8 \cdot 10^{13}$	0.048494851	$\frac{2\pi}{365.25 \cdot 24 \cdot 3600 \cdot 11.862}$	0
Saturn	$1.4 \cdot 10^{14}$	0.055508622	$\frac{2\pi}{365.25 \cdot 24 \cdot 3600 \cdot 29.458}$	0
Uranus	$2.9 \cdot 10^{14}$	0.046295899	$\frac{2\pi}{365.25 \cdot 24 \cdot 3600 \cdot 84.013}$	0
Neptune	$4.5 \cdot 10^{14}$	0.008988095	$\frac{2\pi}{365.25 \cdot 24 \cdot 3600 \cdot 164.794}$	0
Pluto	$6.0 \cdot 10^{14}$	0.248	$\frac{2\pi}{365.25 \cdot 24 \cdot 3600 \cdot 247.686}$	0

Table 2

Planet	Δa_v Eq. (6) (cm)	Δa_1 Eq. (23) (cm)	Δa Present numerical results (cm)
Mercury	0.2206957839	0.2324573618	0.22168
Venus	1.044199404	1.045353061	1.0488
Earth	2.373844135	2.384145714	2.3690
Mars	6.911043753	7.077387973	6.8046
Jupiter	146.3728602	148.2003297	145.9688
Saturn	631.7483878	640.7767262	652.952
Uranus	3901.387136	3947.887234	3838.938
Neptune	11701.87184	11729.51855	11701.188
Pluto	24021.61369	25570.68070	23075.000

Acknowledgements. The author wish to express his gratitude to professor Ioan M. Pop and dr. Tiberiu Oproiu for useful comments and references.

REFERENCES

1. Gylden H., Astron. Nachr., Bd.109, 1884 pp.1–6.
2. Hadjidemetriou, J., *Two-body problem with variable mass: a new approach*, Icarus, **2**, 404 (1963).

3. Hadjidemetriou, J., *Analytic solutions of the two-body problem with variable mass*, Icarus, **5**, 34–46 (1966).
4. Jeans, J.H., *Astronomy and Cosmogony*, Dover Publications, New York, 1961, pp. 298–301 (Reprinted from Cambridge University Press, 2nd Edition, 1929).
5. Meshcherskii, F., *Mechanics of variable mass* (in Russian), Moskow, 1952.
6. Muchametkalieva, R.K. and Omarov, T.B., Proceedings of Astrophysics Institute (in Russian), Moskow, Vol. XXVIII, 1976.
7. Pal, A., Şelaru, D., Mioc, V., Cucu-Dumitrescu, C., *The Gylden-type problem revisited: more refined analytical solutions*, Astron.Nachr., **327**, 304–312 (2006).
8. Schröder, K.P. and Robert Cannon Smith, *Distant future of the Sun and Earth revisited*, Mon. Not. R. Astron. Soc. 000, 1–10 (2008).
9. Vescan, T., *Contribuțiuni la teoria cinetică și relativistă a fluidelor reale*, PhD thesis, Cluj, 1939.
10. ****Anuarul Astronomic 1999*, Editura Academiei Române, Bucharest, 1999.